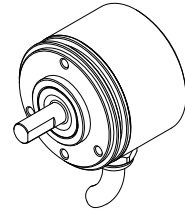


### 1. PGS38 Incremental Optical Encoder (Solid shaft)

#### 1.1 Introduction:

PGS38 is a solid shaft all stainless steel design with a variety of electrical interfaces and resolutions available. The highest protection grade is IP67. It has a compact and sturdy structure, and high safety, commonly used in industrial automation fields in harsh environments.

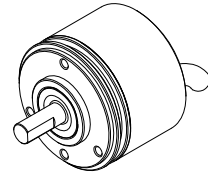
PGS38-T



#### 1.2 Feature:

- Encoder external diameter Ø38mm、thickness 28mm、 diameter of shaft Ø6mm (D type);
- Adopt non-contact photoelectric principle;
- Reverse polarity protection;
- Short circuit protection;
- Multiple electrical interfaces available;
- Resolution per turn up to 32768PPR.

PGS38-Q



#### 1.3 Application:

Outdoor electromechanical, industrial and mining, textile, motor, CNC and other automation control fields.

#### 1.4 Connection:

Cable connection (standard length 1000mm)

#### 1.5 Protection:

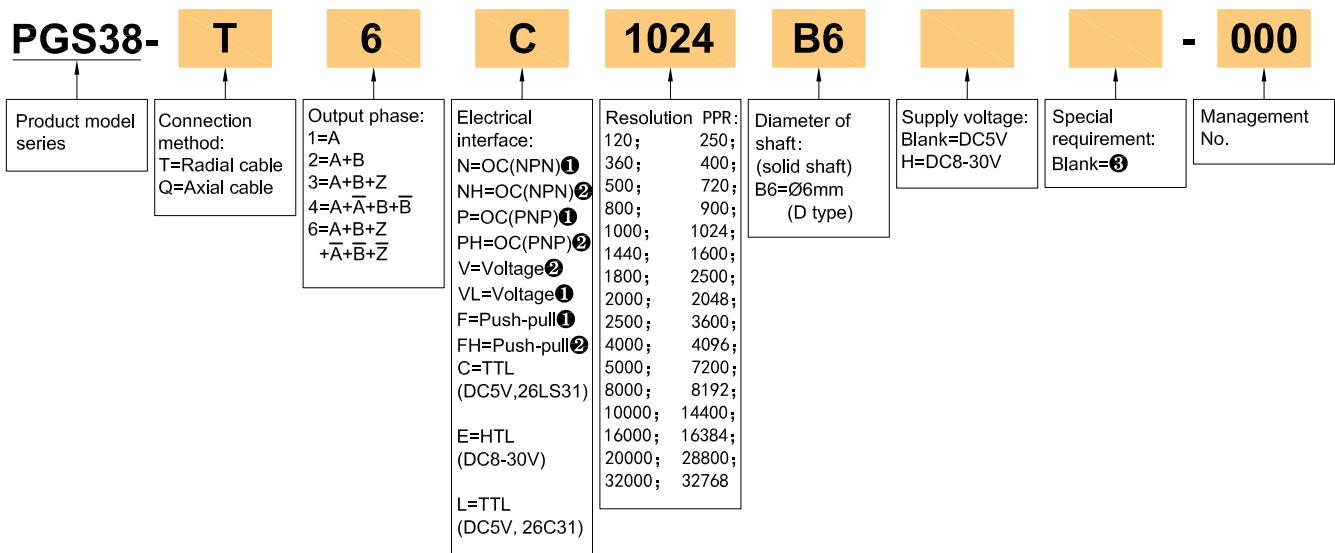
IP67

#### 1.6 Weight:

About 160g

### 2. Model Selection Guide

#### 2.1 Model composition(select parameters)



#### 2.2 Note

- Z signal is low level active.
- Z signal is high level active.
- None indicated for IP67, cable length of 1m, if need to change the length C+number, the longest is 100m (expressed by C100). For the specific length of use, pls refer to page 2 and 3 of the provision of output circuit.

3. Output Method

Electrical interface	Output circuit	Output wave form
<p>OC NPN open collector circuit</p>		<p>a.b.c.d=<math>\frac{T}{4} \pm 8</math></p> <p>Phase A is ahead of B by <math>\frac{T}{4} \pm 8</math>, viewing from shaft end, direction is clockwise rotation. (See dimensional drawings)</p> <p>CW direction →</p> <p>Z signal is low level active</p>
<p>OC PNP open collector circuit</p>		<p>Z signal is high level active</p>
<p>Push-pull</p>		<p>Z signal is high level active</p>
<p>Voltage</p>		<p>Z signal is high level active</p>
<p>TTL (DC5V)</p> <p>HTL (DC8-30V)</p>		<p>a.b.c.d=<math>\frac{T}{4} \pm 8</math></p> <p>Phase A is ahead of B by <math>\frac{T}{4} \pm 8</math>, viewing from shaft end, direction is clockwise rotation. (See dimensional drawings)</p> <p>CW direction →</p> <p>Z signal is high level active</p>

## 4. Electrical Parameters

Parameter Item	Output type	OC	Voltage	Push-pull	TTL	HTL	
Supply voltage		DC+5V±5%; DC8V-30V±5%			DC+5V±5%	DC8-30V±5%	
Consumption current		100mA Max			120mA Max		
Allowable ripple		≤3%rms					
Top response frequency		100KHz			500KHz	800KHz	
Output capacity	Output current	Input	≤30mA	Load resistance 2.2K	≤30mA	≤±20mA	≤±50mA
		Output	—		≤10mA		
	Output voltage	"H"	—	—	≥[(Supply voltage)-2.5V]	≥2.5V	≥V <sub>cc</sub> -3 V <sub>Dc</sub>
		"L"	≤0.4V	≤0.7V(less than 20mA)	≤0.4V(30mA)	≤0.5V	≤ 1V V <sub>Dc</sub>
Load voltage		≤DC30V	—		—		
Rise & Fall time		Less than 2us(cable length: 2m)			Less than 1us(Cable length: 2m)		
Insulation strength		AC500V 60s					
Insulation resistance		10MΩ					
Mark to space ratio		45% to 55%					
Reverse polarity protection		✓					
Short-circuit protection		✓❶					
Phase shift between A & B		90°±10° ( frequency in low speed)					
		90°±20° ( frequency in high speed)					
GND		Not connect to encoder					

❶ Short-circuit to another channel or GND permitted for max.30s.

## 5. Mechanical Specifications

Diameter of shaft	Ø6mm(D type, Stainless steel)
Starting torque	Less than $9.8 \times 10^{-3} \text{N}\cdot\text{m}$
Inertia moment	Less than $6.5 \times 10^{-6} \text{kg}\cdot\text{m}^2$
Shaft load	Radial 30N; Axial 20N
Slew speed	$\leq 6000 \text{ rpm}$
Bearing Life	$1.5 \times 10^9$ revs at rated load(100000hrs at 2500RPM)
Shell	Stainless steel
Weight	about 160g

## 6. Environmental Parameters





Environmental temperature	Operating: $-40 \sim +95^\circ\text{C}$ (repeatable winding cable: $-10^\circ\text{C}$ ); Storage: $-40 \sim +95^\circ\text{C}$
Environmental humidity	Operating and storage: 35~85%RH(noncondensing)
Vibration(Endurance)	Amplitude 0.75mm, 5~55Hz, 2h for X,Y,Z direction individually
Shock(Endurance)	$490 \text{m/s}^2$ 11ms three times for X,Y,Z direction individually
Protection	IP67

### 7. Wiring Table

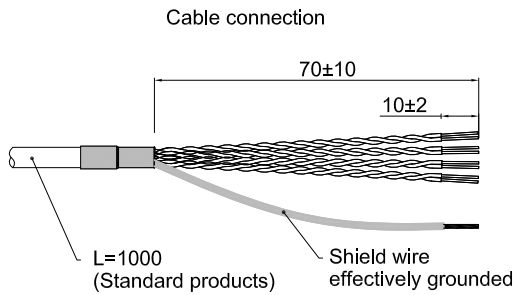
#### 7.1 OC/Voltage/Push-pull

	Supply voltage		Incremental signal		
Wire color	Red	Black	White	Green	Yellow
Function	Up	Un	A	B	Z

#### 7.2 TTL/HTL

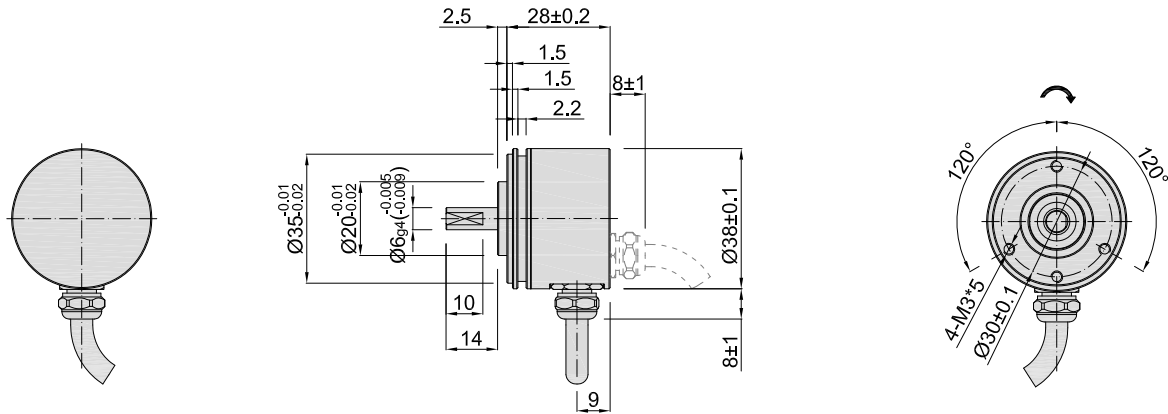
	Supply voltage		Incremental signal					
Wire color	Red	Black	White	White/BK	Green	Green/BK	Yellow	Yellow/BK
Function	Up	Un	A+	A-	B+	B-	Z+	Z-
Twisted-paired cable								

Up=Supply voltage.  
 Shield wire is not connected to the internal circuit of encoder.



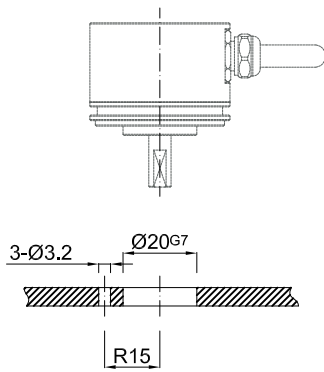
### 8. Basic Dimension

#### 8.1 Dimension

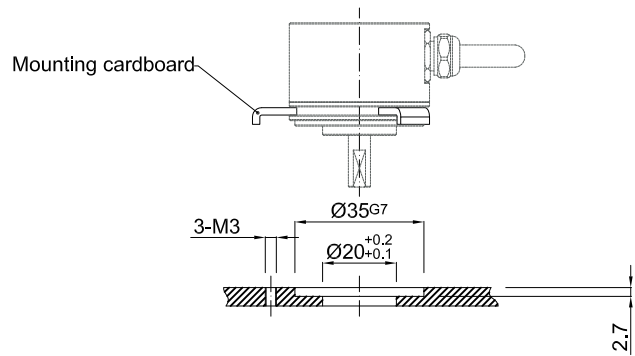


#### 8.2 Installation method

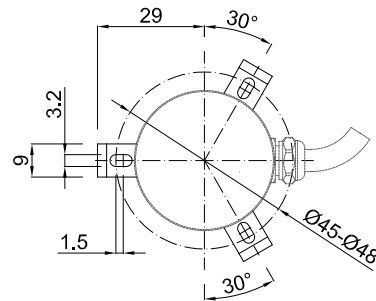
##### Installation method 1:



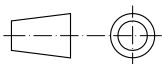
##### Installation method 2:



Mounting screws
Inner hexagon bolt +flat washer Specification: M3*10 Material: stainless steel Quantity: 3



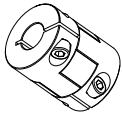
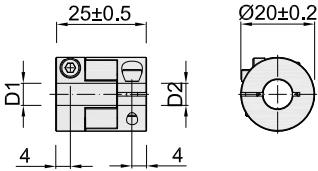

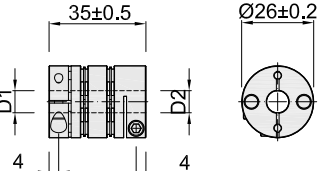
Unit: mm




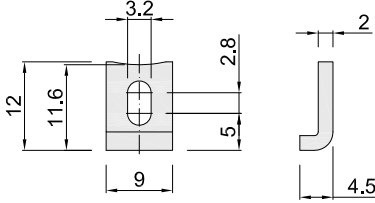
↻ = Shaft rotation direction of the signal output

9. Recommended Accessories

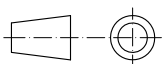
9.1 Coupler

Coupler	Dimension	D1	D2	Model	Order No.
Cross type: M series 	 <p>Main body material: aluminum alloy</p>	Ø6 <sup>G8</sup>	Ø6 <sup>G8</sup>	6M6	08700037
		Ø6 <sup>G8</sup>	Ø8 <sup>G8</sup>	6M8	08700038
Diaphragm type: W series 	 <p>Main body material: aluminum alloy</p>	Ø6 <sup>G8</sup>	Ø6 <sup>G8</sup>	6W6	08700041
		Ø6 <sup>G8</sup>	Ø8 <sup>G8</sup>	6W8	08700042

9.2 Mounting cardboard

Mounting cardboard	Dimension	Model	Order NO.
 3 pcs as a set	 <p>Material: stainless steel</p>	39K46	03700722

Unit: mm



## 10. Caution

### 10.1 Caution for operation

- The working temperature shall not exceed the storage temperature.
- The working humidity shall not exceed the storage humidity.
- Do not use where the temperature changes dramatically and have fog.
- Do not close to corrosive and flammable gas.
- Keep away from dust,salt and metal powder.
- Keep away from places where you will use water, oil, or medicine.
- Undue vibration and shock will impact the encoder.

### 10.2 Caution for Installation

- Electrical components should not be subjected to excessive pressure, etc., and electrostatic assessment of the installation environment should be conducted.
- Do not close the cable of the motor power to the encoder.
- The FG wire of the motor and mechanical device should be grounded.
- The shielding wire must be effectively grounded since the shielding is not connected to the encoder.

### 10.3 Caution for wiring

- Use the encoder under the specified supply voltage. Please note that the supply voltage range may drop due to the wiring length.
- Do not put the encoder wiring and other power lines through the same duct, and do not use them by bundling in parallel.
- Please use twisted pair wires for the signal and power wires of encoder.
- Please do not apply excessive force to the cable of encoder, or it will may be damaged.